

A magnetic starter with low voltage and thermal overload protection gives the most satisfactory service. These starters may be controlled by remote push button stations, thermostats, or pressure switches to meet the requirements of any particular installation.

The high torque, low starting current motor has a starting current approximately the same as the normal torque, low starting current motor when started on full voltage. These motors, most commonly used on compressor drive, can be started directly across-the-line with manual or magnetic starters.

MULTISPEED MOTOR CONTROL

To make an installation more flexible, multispeed motors are available with two, three or four speed designs, with variable torque, constant torque or constant horsepower characteristics. Multispeed motors may be started by means of manual or magnetic starting equipment.

When using automatic magnetic control with two, three, and four speed separate winding or consequent pole motors, control is obtained from a remote point by means of a push button master switch. The various speeds of the motor are obtained from the master switch by simply depressing the correct push button, which is known as selective speed control. It is commonly used in the smaller theater installations where the fan and motor are located backstage and the speed control is located in the lobby.

Magnetic multispeed motor controllers may also be provided with a compelling relay which makes it necessary that the operator press the first speed button before regulating the motor to the desired speed. This assures the operator that the motor is always started at low speed before the motor is adjusted to one of the higher speeds. Starting on low speed limits the starting current to the starting current of the low speed winding, and therefore, permits the use of motors in sizes larger than ordinarily permitted by central stations for full voltage starting.

Timing relays, which provide for automatic acceleration, may be used for control. With the automatic acceleration feature, it is only necessary to press the button for the desired speed. The motor will always start in low speed and automatically step up to the desired speed. Decelerating relays are used on multispeed compressor motors, in order to reduce the effect of the braking action and shock to the motor, compressor and drive, when the speed is to be reduced from a higher to a lower speed.

Where the change of speeds does not occur at regular intervals, and where it is only necessary to change from one speed to another to take care of seasonal requirements, a manual drum speed selector may be used. This drum is used to select the proper motor speed while an automatic starter is used to start and stop the motor.

The smaller size speed selector drums rated 10 hp at 220 volts and smaller may also be used as a motor starter to make and break the current, as well as serving as a speed selector device. Reversible or non-reversible drums may be supplied depending on the requirements of the installation.

In the large size drums, a separate contactor must be provided to make and break the current. The contactor may be any approved starter.

Overload and low voltage protection may be accomplished by using a magnetic starter. No push button station is required, the handle switch on the drum having the same characteristics as a three wire push button station.

In selecting two speed motors for fan, pump, blower, or compressor drive it will be found that the two winding motors are more expensive than the single winding. The control for two speed, two winding motors is more economical and the combined price of the motor and contactor is only slightly higher. Because of the better performance of the two speed motor and the factor of safety in having two independent motor windings, the increased cost is considered worth the difference.

WOUND ROTOR MOTOR CONTROL

When close speed regulation and low starting current are required slip ring or wound rotor motors are used. Wound rotor induction motors are built for two classes of service, constant speed and adjustable varying speed. The motors for the two classes of service are identical, the only difference being in the secondary control used with the motors. Control for both primary and secondary of a slip ring motor is required.

The primary control for a constant or adjustable speed is the same type as used with squirrel-cage motors. Manual or magnetic starters, across-the-line type, may be used depending on the installation.

The starting current and starting torque of a slip ring motor are almost entirely dependent on the amount of resistance in the secondary control and in the manner in which the secondary control is operated. The resistance for the secondary control is usually of the cast-iron grid construction and the amount of the resistance in the circuit is controlled by a multi-point drum or cam switch which can be manually or automatically positioned. The *National Electric Manufacturers Association* has adopted service classifications which allow a selection of resistors permitting a starting current on the first contact of resistance varying from approximately 25 per cent of full load current to approximately 200 per cent of full load current or more, and permitting the resistor to remain in the secondary circuit of the motor for a period varying from not more than 15 seconds during an interval of operation from 4 minutes to continuous.

Speed adjustment of a wound rotor induction motor is obtained by inserting resistance in the secondary circuit and usually provides for a 50 per cent speed reduction when the motor is selected for constant torque service for full load at maximum speed. For variable torque duty, such as fans drives, wound rotor motors and control are suitable for speed reduction to 25 or 30 per cent of full load speed. As resistors are supplied for both fan duty and constant torque duty, care should be taken in selecting the proper resistors.

Wound rotor induction motors when used with centrifugal pumps and fans should have fan duty resistors. Because of the low current inrush of the fan and pump load a starting resistor *NEMA* classification No. 15 may be used. For speed regulation-resistor, classification No. 93 should be selected. On a compressor drive using an unloader, a constant torque resistor classification No. 15 should be used. If the compressor is started