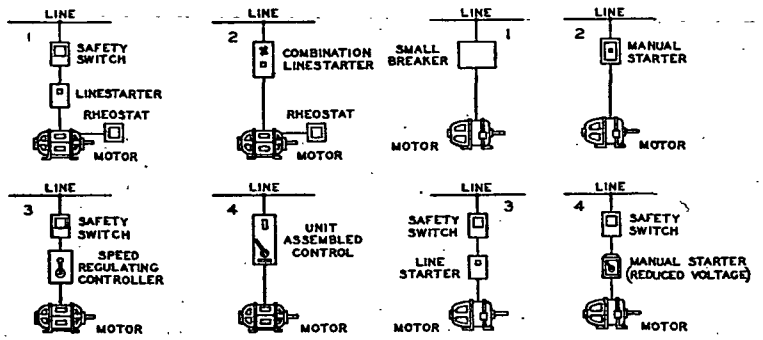
Multi-Speed control may be either manual or magnetic, and at full or reduced voltage. When using automatic magnetic control with two-, three-, and four-speed separate winding or consequent pole motors, control may be obtained from a remote point by means of a push button master switch. The various speeds of the motor are obtained from the master switch by simply depressing the correct push button. This is known as selective speed control. It is commonly used in the smaller theater installations where the fan and motor are located backstage and the speed control is located in the lobby.

Multi-speed motor controllers may be provided with compelling relays which make it necessary for the operator to press the first speed button before regulating the motor to the desired speed. This insures that the motor is always started at low speed before adjusting to a higher speed.

Timing relays which provide for automatic acceleration may be used for control. With this feature the motor will always start at low speed



Arrangements 2, 3 and 4 are optional for motors up to 7½ hp, 220 volts.

FIG. 12. RECOMMENDED CONTROLS FOR WOUND ROTOR MOTORS

FIG. 13. RECOMMENDED CONTROLS FOR SINGLE PHASE MOTORS

and automatically accelerate to the desired speed. Decelerating relays may be used to reduce the shock effect of the braking action on the motor and drive when the speed is reduced from a higher to a lower speed.

Single Phase motor control usually consists only of a linestarter, either manual or magnetic. In some cases it is desirable also to provide a disconnect switch. Fig. 13 illustrates the recommended controls.

Typical specifications for single phase motor control are shown in Specification J at end of chapter.

GEAR MOTORS

A gear motor is a self-contained combination of any type of a-c or d-c motor and an enclosed speed-reducing gear, providing a more compact and readily adaptable unit than is obtained by using a motor coupled to a gear reducer. Gear motors are available in sizes up to 75 hp with output shaft speeds from about 4 to 1430 rpm, making it possible to couple or to connect by gear or chain to nearly any machine. High speed motors are used, generally 1800 rpm on 60 cycles, thus obtaining the advantages of

high motor power factor and efficiency. The gearing efficiency is also high, usually about 98 per cent for a single reduction of the helical or spur type, that is, a 2 per cent loss for one reduction or 4 per cent loss for a double reduction. Consequently, the overall performance of the gear motors is much higher than a combination of open gearing, belting, countershaft, or other arrangement, which would otherwise be required. Gear motors are used extensively to drive numerous types of slow speed drives. Besides being more effective than other combination drives in saving space, they are important in reducing maintenance and operating hazards.

MOTOR RATING

The rating of an electric motor depends upon the total temperature which the motor attains under operating conditions. This total temperature depends on both the ambient temperature and the temperature rise of the motor. As motor temperature rise is in turn determined by the ability of the motor to dissipate heat, circulation to the motor should not be restricted. Improper selection of motors with regard to temperature ratings may result in high motor operating temperatures with accompanying reduction in motor life.

In general, the electrical insulation is the portion of the motor most susceptible to injury from high operating temperatures. Of the several types of insulation which are available, the most common type, specified as Class A by the *National Electrical Manufacturers Association*, consists of cotton, felt, paper or similar organic materials, and permits a 55 C rise in temperature over a 40 C ambient temperature for totally enclosed motors. Class B insulation consists of mica, asbestos, fiber glass, or similar inorganic materials, and permits a 75 C rise in temperature over the 40 C ambient for totally enclosed motors. Other types of insulation such as silicone resin are available and permit much higher operating temperatures.

The mechanical construction of the different types of motor enclosures, and the rise in temperature with Class A insulation for each type, are enumerated in the glossary at the end of this chapter. Since the difference between the hottest spot and the maximum observable temperature, as measured by a thermometer, is greater for an open machine than for an enclosed machine, the permissible temperature rise is 50 C for an open motor.

FUNCTIONS OF CONTROL EQUIPMENT FOR MOTORS

In general, control equipment for all types of motors should provide: (1) means of disconnecting the motor from the power supply; (2) means for starting the motor; (3) overload protection for the motor; (4) protection against low voltage; and (5) means for varying the motor speed.

Full voltage starting for motors is preferable because of its lower first cost and simplicity of control. Except for d-c machines, most motors are mechanically and electrically designed for full voltage starting. The starting inrush current, however, is limited in many cases by regulations of power companies because of the voltage fluctuations which may be caused by heavy current surges. It is therefore often necessary to reduce the starting current below that obtained by across-the-line starting. The power supplier should be consulted to determine the allowable inrush current for any given location.

The choice between full voltage and reduced voltage starting is governed