

Single Phase Motors

Capacitor type motors are available in ratings up to 10 or 15 hp for general purposes. These motors are recommended for pumps, compressors and fan duty including housed centrifugal fans and propeller fans. The general purpose motor is commonly known as a high torque capacitor motor having approximately 300 per cent starting torque with normal current and having a different value of capacitance for starting and running which is automatically changed over by a mechanical or electrical means.

Capacitor motors for *fan duty* are usually divided into the open high torque type for belted fans and the totally inclosed non-ventilated low torque type for propeller fans mounted directly on the motor shaft. The open low torque capacitor motor may be used with small centrifugal fans mounted on the motor shaft.

Although the motors for *belted fans* are called high torque, the available starting torque is somewhat less than the torque of the general purpose motor and the slip at full load is approximately 8 per cent. With this larger amount of slip, adjustable speed down to 60 or 70 per cent of rated speed may be obtained by line voltage variation. Motors for *propeller fan* drive may be supplied with sleeve bearings to obtain greater quietness in the smaller sizes where the fan thrust does not exceed approximately 25 lb. For larger fans, thrust ball bearing motors should be used. Low torque capacitor motors have approximately 50 per cent starting torque and do not change the value of capacitance from start to run.

Capacitor motors with *high slip* may have taps brought out from the main winding which when connected to the line, give a second speed of from 65 to 70 per cent of the normal speed. This type of motor must be specially designed for the individual fan, otherwise the correct low speed will not be obtained. Care should be exercised in applying it to centrifugal fans where restriction to the air flow through the use of adjustable dampers changes the motor load and consequently the speed. This same effect is also found in transformer speed controllers, however, a series of transformer taps allow for a selection which partially overcomes the effect of change in motor load.

Capacitor start-induction run motors are usually confined to the smaller horsepower ratings and differ from the capacitor motors by having no running capacitor. The value of starting capacitance used may vary with the different types of applications involved. These motors may be used for practically any of the applications met in air conditioning. However, consideration should be given to the fact that they are not as quiet as a capacitor motor.

Repulsion induction motors start as repulsion motors and operate under full speed as combined repulsion and induction motors through the inherent characteristics of the motor which has, in addition to the wire winding with commutator, a buried squirrel cage winding. No additional switching devices are required to change over from start to run. This and the repulsion motor described below may be used for constant speed drives where high starting torque is required and where commutator and brush noise is not a factor.

The *repulsion start-induction run* motor starts as a repulsion motor, has a switching means for transferring from start to run which short circuits the commutator and permits operation under full speed as a wound induction motor. This motor is suitable for applications similar to those for which the repulsion induction motor is used.

The *split phase* motor has a high resistance auxiliary winding in the circuit during starting which is disconnected through the action of a centrifugal switch as the motor comes up to speed. Under running conditions, it operates as a single phase induction motor with one winding in the circuit. These units are available for the lower horsepower ratings and when equipped with a high slip rotor may be used for adjustable varying speed through line voltage control.

Polyphase Motors

Squirrel cage induction motors are available in three types and a full range of sizes:

1. The normal torque, normal starting current squirrel cage motor has close speed regulation, high efficiency, high power factor, medium starting torque, high pull-out torque, and is suitable for general purpose applications. This motor has a large current inrush and a low starting current power factor. It operates with these characteristics only when started directly across the line on full voltage. When central stations require current limiting starting equipment on such motors, the starting torque is less. Current limiting hand operated starters are standard equipment.

2. The normal torque, low starting current squirrel cage motor has approximately the same torque as the normal current motor, but the starting current is about 20 per cent less than the normal torque motor on full voltage and ordinarily within the *Edison Electric Institute* locked rotor current limits on sizes up to 30 hp.

This motor lends itself to automatic or remote control because no current limiting starting equipment is necessary up to and including 30 hp. A magnetic starter with low voltage and thermal relay overload protection gives the most satisfactory service.

3. The high torque, low current squirrel cage motor has a starting torque approximately 25 to 50 per cent greater than the normal torque motor on full voltage with starting current approximately 10 per cent less than the normal torque motor started on full voltage, but within the required limits on 30 hp sizes and smaller. These motors are also started directly across the line on full voltage through a magnetic starter or other approved starting device.

These three types of motors are also available in two, three, or four speed designs with variable torque, or constant torque characteristics. Two speed motors may be either single, or two winding; three speed motors are single, two, or three winding; and four speed motors are two, three, or four winding. When a motor is wound with a winding for each speed, better operating characteristics may be obtained because no sacrifice is made for the other speed and operating characteristics approaching single winding motors may be expected.

Frequently, multispeed motors lend flexibility to an installation that cannot be obtained in any other way.

Multispeed motors are started directly across the line through magnetic starting equipment with overload and low voltage protection and compelling relays to insure starting on low speed regardless of the ultimate running speed. Starting on low speed limits the starting current to the starting current of the low speed winding and consequently lowers the maximum demand.